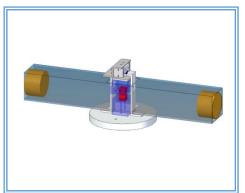


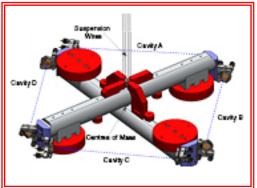
#### Goals and Projects

- Increase the sensitivity and duty cycle of GW detectors across the entire frequency band by improving the low frequency stability
- Measure low frequency seismic noise to estimate Newtonian noise
- 3. To directly measure Newtonian noise

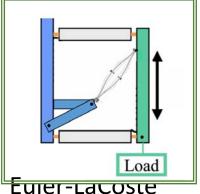




Tilt meter—ALFRA



TorPedDo Sensor



ULF pre-isolator



CDS: LIGO type digital control

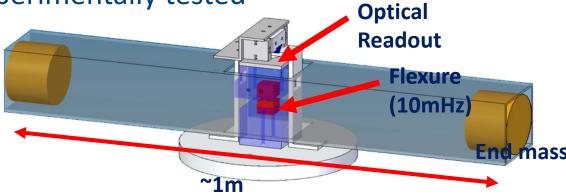


# Advanced Low Frequency Rotation Sensor WESTERN AUSTRALIA

#### Advanced Low Frequency Rotation Accelerometer (ALFRA)

- Sensing the ground tilt and feedback to the isolation stage to reduce horizontal to tilt coupling
- Could be mounted in any orientation
  - Modelling complete
  - Bar in manufacturing stage
  - Flexure design complete
  - Vacuum chamber designed and under construction

Optical readout experimentally tested



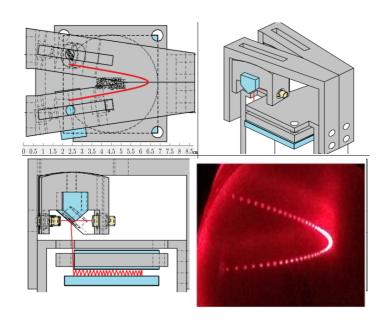


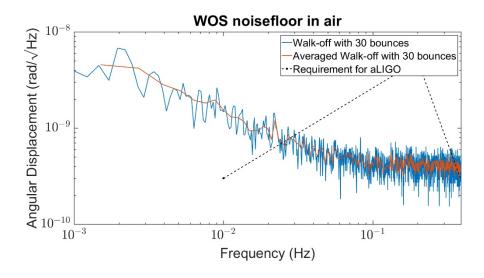
#### Walk-off sensor (WOS)



#### Optical readout system for ALFRA

- Readout system tested
- Paper ready for P&P
- Integrated design complete





- Readout Sensitivity on table top (in air):
  - Seveal nrad/rt(Hz) > 1mHz
  - 0.4nrad/rt(Hz) >100mHz
- Needs to go into vacuum



See Joshua McCann's poster

#### TorPeDo Seismic Chain Design



Torsion Pendulum Dual Oscillator (TorPeDO)

--low frequency gravitational force sensor

Inverted Pendulum

- MultiSAS base
- Uses 3 Trilliums to isolate linear motion
- · Soft platform for actuation
- Contains GAS filter for vertical isolation.

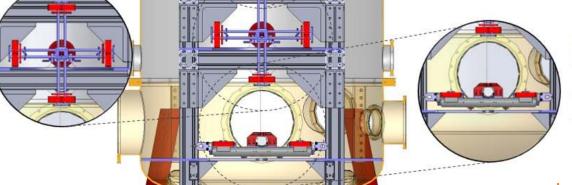
Torpedo Sensor is operating with its initial control prototype running on a continues basis.



- 140kg 6-way cross / hollow sphere hybrid
- Large inertia combined with single wire suspension provides high passive isolation.
- Spherical structure raises the frequency of internal modes.
- 6-way cross allows for fine tuning of CoM and moment of inertia.



- 40kg 6-way cross.
- Acts as suspension point for TorPeDO system.
- High moment of inertia per mass provides additional isolation for rotation.

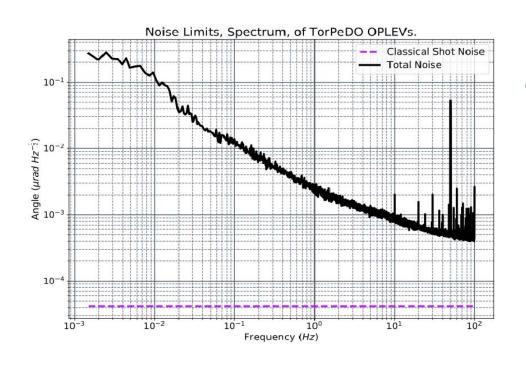


#### TorPeDO System

- Two dual wire torsion pendulums.
- Operation between 30mHz to 10Hz.
- Optical differential yaw readout.

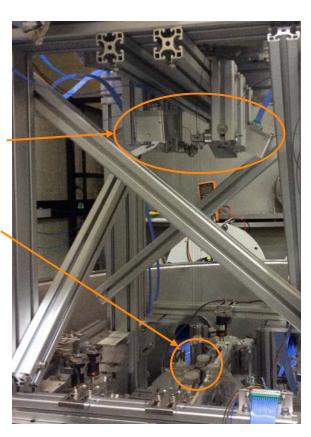
### TorPeDO Local Sensing and Damping





Collimators (x4) and Quadrant Photodiodes (x4).

Mirrors (x4)



Optical levers have been implemented on the TorPeDO for sensing:

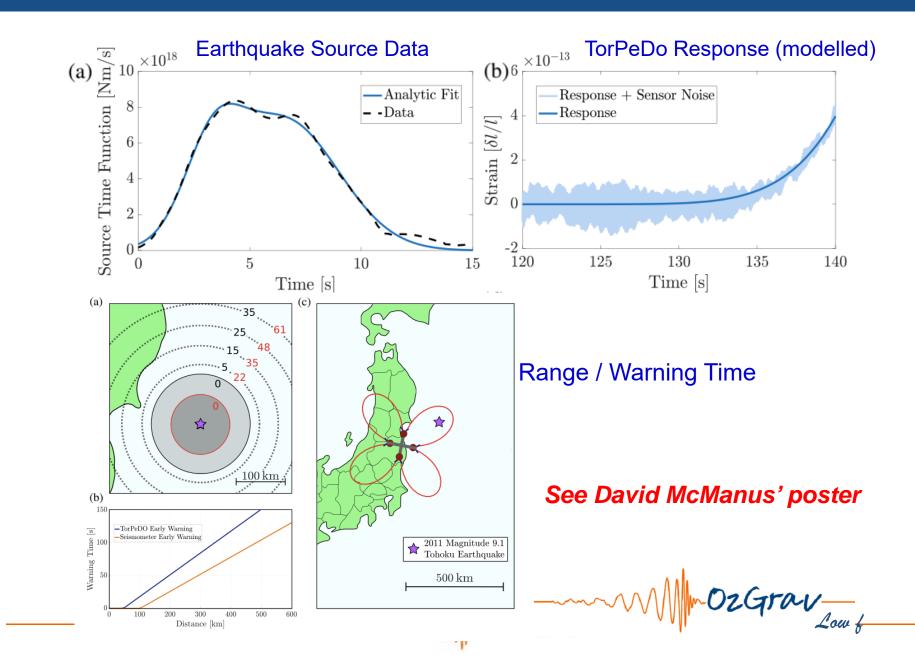
- ➤ Pitch, Roll and Vertical modes.
- ➤ We now have control of all six degrees of freedom of each bar.

See poster by Nathan A. Holland, et al.



#### Sensor response and Detection

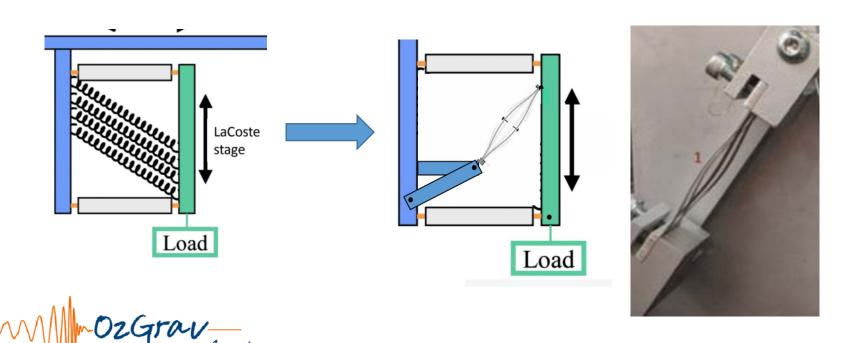




## Euler-LaCoste ULF pre-isolation stage



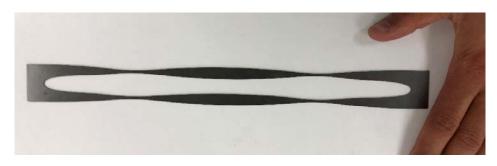
- Replacing the coil spring in LaCoste stage with maraging steel Euler springs
  - Reducing the creep of the coil spring
  - Higher internal frequency of the spring elements



#### Improved Euler Spring design



- New Euler blade shape designed and tested
- Euler-LaCost designed
- Frame under construction



- Special shape with uniform stress and minimum blade mass
- Monolithic double blade for symmetry and minimum clamping loss.

See Joris van Heijningen's poster



# Contoured Euler springs in compression tester



# Control and Data acquisition System (CDS) @ ANU and UWA

- LIGO type digital control system CDS are operational in both groups
  - Extensive discussions between the groups
  - With the help from Keith Thorne (LLO), problems are being discussed and solved



#### Exchange and Collaboration

- Weekly low frequency program zoom meeting
- Sharing ideas, experiences, tips and tricks
- UWA PhD Joshua McCann visited ANU for 2 weeks in June

#### Next....

- Instruments running
- More mutual visits



